

The Inversion Formula ~ Starting the Conformal THERMAL Bootstrap

didn't get here in

Motivation

→ Bootstrap @ $T=0$: Aim to constrain CFT data $\{ \Delta_\sigma, J_\sigma \}$, $\{ f_{\sigma_1 \sigma_2 \sigma_3} \}$

↳ Conformal dimension
 ↳ structure constants (coefficients in OPE)
 ↳ spin

↳ How?

- Conformal Symmetry (1)
- OPE (2)
- Crossing Symmetry (3)

→ Bootstrap @ $T=1/\beta$ (i.e. finite & non-zero)

↳ How?

• Quantize on $\mathcal{M}_\beta^d = S^1 \times \mathbb{R}^{d-1}$ where S^1 corresponds to the Euclidean time

↳ Why?

- Quantum Critical Points always have non-zero temperature in the laboratory.
- For $d > 2$, $\mathcal{M}_\beta^d \neq \mathbb{R}^d$ critically no ideally, any non-pert. solution of a QFT should describe its observables on arbitrary manifolds.
- In holography context, FTCFT's are dual to AdS black holes.

Background/Overview

→ From last week: $\mathbb{R}^{d-1} \times S^1$ breaks conformal symmetry (1) but we have spatial rotations, translations, 'scale invariance'.

→ \mathcal{M}_β^d is conformally flat, locally $\mathcal{M}_\beta^d \cong \mathbb{R}^d$, so we can compute two-point functions using the OPE, assuming Δx is sufficiently small.

↳ But we have new data, thermal one-point functions.

↳ 1-point fct. $\langle \mathcal{O} \rangle_\beta = \frac{b_\mathcal{O}}{\beta^{\Delta_\mathcal{O}}}$

↳ scalar operator

- Here the β dependence is fixed by scale symmetry
- The coeff. $b_\mathcal{O}$ is not fixed

↳ 2-point fct. $g(\tau) \equiv \langle \phi(\tau) \phi(0) \rangle_\beta \sim \frac{1}{|\tau|^{2\Delta_\phi}} \sum_{\mathcal{O} \in \beta \neq \phi} \frac{f_{\phi\phi\mathcal{O}} b_\mathcal{O}}{c_\mathcal{O}} \left| \frac{\tau}{\beta} \right|^{\Delta_\mathcal{O}}$

↳ OPE coeff. of \mathcal{O}

↳ Scaling dim of \mathcal{O}

↳ 2-point coefficient in vacuum

! Only chosen separation in the circle direction of distance τ

→ we have the KMS condition:

$$g(\tau) = g(\beta - \tau)$$

Q: Does $g(\tau)$ given satisfy the KMS condition?

A: No!

→ From KMS we retrieve a "thermal crossing equation" → (3)

↳ This constrains $b_\mathcal{O}$ in terms of CFT data, → $f_{\phi\phi\mathcal{O}}$ and $\Delta_\mathcal{O}$

↳ From the limit $S^1 \times S^{d-1} \rightarrow S^1 \times \mathbb{R}^{d-1}$ we can see the "crossing symmetry" ~ usual case of crossing symmetry for 4-point functions where we sum over some external operators

↳ so $\sum_{i_2} \sum_{i_4} \langle \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \mathcal{O}_4 \rangle = \langle \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \mathcal{O}_4 \rangle ?$

→ Goal: The thermal bootstrap ↔ Compute all by using KMS and zero temp CFT data

Ch1: Zero-Temp Recap

• Any CFT T_n on \mathbb{R}^d can be computed using OPE.

• Eg:

$$\langle \mathcal{O}_1(x_1) \mathcal{O}_2(x_2) \dots \mathcal{O}_n(x_n) \rangle = \sum_{k_1} C_{12k_1} \langle \mathcal{O}_{k_1} \mathcal{O}_3 \dots \mathcal{O}_n \rangle$$

$$= \sum_{k_1} \dots \sum_{k_{n-1}} C_{12k_1} C_{k_1 k_2 k_3} \dots C_{k_{n-2} k_{n-1}} \langle \mathcal{O}_{k_{n-1}} \rangle$$

• Consider 3-point:

↳ OPE defines an algebra $\mathcal{O}_i * \mathcal{O}_j = \sum_k C_{ijk} \mathcal{O}_k$

↳ Associative: $(\mathcal{O}_i \mathcal{O}_j) \mathcal{O}_k = \mathcal{O}_i (\mathcal{O}_j \mathcal{O}_k)$

$$\langle \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \rangle = \sum_{k_1} \frac{C_{12k_1}}{|x_{12}|^{\Delta_1 + \Delta_2 - \Delta_{k_1}}} \langle \mathcal{O}_{k_1} \mathcal{O}_3 \rangle$$

$$= \sum_{k_1} \frac{C_{12k_1}}{|x_{12}|^{\Delta_1 + \Delta_2 - \Delta_{k_1}}} \frac{\delta_{k_1 3}}{|x_{23}|^{2\Delta_3}}$$

↳ $\mathcal{O}_{k_1} = \mathcal{O}_3 = \mathcal{O}$

$$= \frac{C_{123}}{|x_{12}|^{\Delta_1 + \Delta_2 - \Delta_3} |x_{23}|^{2\Delta_3}}$$

• Conformal symmetry fixes 3-point:

$$\langle \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \rangle = \frac{C_{123}}{|x_{12}|^{\Delta_1 + \Delta_2 - \Delta_3} |x_{23}|^{\Delta_2 + \Delta_3 - \Delta_1} |x_{31}|^{\Delta_1 + \Delta_3 - \Delta_2}}$$

↳ In limit $x_1 \rightarrow x_2$ do we recover * ?

$$\approx \frac{C_{123}}{|x_{12}|^{\Delta_1 + \Delta_2 - \Delta_3} |x_{23}|^{2\Delta_3}}$$

$$|x_1 - x_2| \ll |x_1 - x_3|, |x_2 - x_3|$$

$$\Rightarrow |x_1 - x_3| = |(x_1 - x_2) + (x_2 - x_3)| \lesssim |x_2 - x_3|$$

$\underbrace{\hspace{10em}}_{\ll a}$

$$\stackrel{\text{so}}{\sim} |x_{23}| \ll |x_{31}| \rightarrow |x_{13}|^{\Delta_1 + \Delta_3 - \Delta_2} \times |x_{23}|^{\Delta_2 + \Delta_3 - \Delta_1} \approx |x_{23}|^{2\Delta_3} \checkmark \text{ as expected}$$

• First interesting case @ 4pt:

↳ contains all dynamical info

$$\langle \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \mathcal{O}_4 \rangle = \frac{1}{|x_{12}|^{\Delta_1 + \Delta_2} |x_{34}|^{\Delta_3 + \Delta_4}} G(u, v)$$

where u, v are cross-ratios

$$u = \frac{x_{12}^2 x_{34}^2}{x_{13}^2 x_{24}^2}, \quad v = \frac{x_{14}^2 x_{23}^2}{x_{13}^2 x_{24}^2}$$

↳ Now consider OPE

$$\langle \mathcal{O}_1(x_1) \mathcal{O}_2(x_2) \mathcal{O}_3(x_3) \mathcal{O}_4(x_4) \rangle \sim \sum_{\mathcal{O}} C_{12\mathcal{O}} \frac{1}{|x_{12}|^{\Delta_1 + \Delta_2 - \Delta_{\mathcal{O}}}} \underbrace{\langle \mathcal{O}(x_3) \mathcal{O}_3(x_3) \mathcal{O}_4(x_4) \rangle}_{\text{fixed by conformal symmetry}}$$

$$\sim \sum_{\mathcal{O}} C_{12\mathcal{O}} \frac{1}{|x_{12}|^{\Delta_1 + \Delta_2 - \Delta_{\mathcal{O}}}} \frac{C_{\mathcal{O}34}}{|x_{23}|^{\Delta_{\mathcal{O}} + \Delta_3 - \Delta_4} |x_{24}|^{\Delta_{\mathcal{O}} + \Delta_3 - \Delta_3} |x_{34}|^{\Delta_3 + \Delta_4 - \Delta_{\mathcal{O}}}}$$

• So $G(u, v) = \sum_{\mathcal{O}} C_{12\mathcal{O}} C_{\mathcal{O}34} G_{\mathcal{O}, \Delta_{\mathcal{O}}}(u, v; \Delta_i)$

CROSSING EQUATION

$$\sum_{\mathcal{O}} C_{12\mathcal{O}} C_{\mathcal{O}34} G_{\mathcal{O}, \Delta_{\mathcal{O}}}(u, v) = \sum_{\mathcal{O}} C_{13\mathcal{O}} C_{\mathcal{O}24} G_{\mathcal{O}, \Delta_{\mathcal{O}}}(v, u; \Delta_i) = \sum_{\mathcal{O}} C_{14\mathcal{O}} C_{\mathcal{O}23} G_{\mathcal{O}, \Delta_{\mathcal{O}}}\left(\frac{u}{v}, \frac{v}{u}\right)$$

Ch. 2 Non-Zero Temp

• But @ $T = 1/\beta$ we know $\langle \mathcal{O} \rangle \neq \begin{cases} 0 & \text{otherwise} \\ 1 & \text{if } \mathcal{O} = 1 \end{cases}$ ↳ Assume unitarity so only the unit op. has scaling dim = 0
its more complicated

- 1) Non-Unit operators can have non-zero one-point functions.
- 2) Depending on the configuration of operator insertions, it may not always be possible to perform the OPE.
↳ Specifically, to compute $\mathcal{O}_i \times \mathcal{O}_j$ we must find a sphere containing only \mathcal{O}_i and \mathcal{O}_j whose interior is flat (possibly after a Weyl transform... so conformally flat?), but this may not be possible for a M^d

• Here $M^d = S^1_{\beta} \times \mathbb{R}^{d-1}$, co-ords $x = (\tau, \mathbf{x})$ where τ is periodic $\tau \sim \tau + \beta$

• So what symmetries constrain 1-point fncts?

1. Translation invariance

- Implies descendants have vanishing 1-pt. fncts.

$$\langle P^{\mu} \mathcal{O}(x) \rangle_{\beta} = \partial^{\mu} \langle \mathcal{O}(x) \rangle_{\beta} = \partial^{\mu} \langle \mathcal{O}(0) \rangle_{\beta} = 0$$

E.g. $\langle \mathcal{O}^a(x) \mathcal{O}^b(0) \rangle = \frac{I^{ab}(x)}{|x|^{2\Delta}}$ where if \mathcal{O} = scalar then $I^{ab} = \delta^{ab} = 1$

conformal group $SO(d+1, 1)$, $\mathcal{O}(x)$ transforms simply under conformal transformations + annihilated by K_{μ} (gen. SC's op)
 ↳ Under rotations ($SO(d)$) the comp. of $\mathcal{O}(x)$ can transform in a rep. ρ of $SO(d)$. ρ = scalar, vector, STTs, ...

2. Focus on ^{symmetry} primary operators: \mathcal{O} w/ dimension Δ and $SO(d)$ rep. ρ in a rep. ρ of $SO(d)$.

- For the geometry $S^1 \times \mathbb{R}^{d-1}$ we have $SO(d-1)$

- As well as discrete symmetry where $\tau \leftrightarrow -\tau$ ↳ Note: Not guaranteed parity \therefore accompany discrete time-reversal w/ reflection in one direction on \mathbb{R}^{d-1}

⇒ These symmetries together give symmetry group $O(d-1) \subset SO(d)$

↑ If we have parity then $O(d-1) \times \mathbb{Z}_2$

• So for $\langle \mathcal{O} \rangle_{\beta} \neq 0$ we need the restriction of ρ under $O(d-1) \subset SO(d)$ to contain trivial rep.

Res $SO(d)$
 $O(d-1) \rho = 1$ ← trivial rep.
 ↗ restriction

• Rep. ρ of group G $\rho: G \rightarrow GL(V)$ where V is a vector space s.t.
 $\rho(g_1 g_2) = \rho(g_1) \rho(g_2)$ $g_1, g_2 \in G$
 • Suppose $H \subset G$ is a subgroup, to restrict ρ to H means
 $\rho|_H: H \rightarrow GL(V)$, $\rho|_H$

• Therefore:

Trivial rep requirements mean $\rho = \text{STT}$, with even spin J . $\therefore \langle \mathcal{O}^{N_1 \dots N_J} \rangle \sim (e^{N_1} \dots e^{N_J} - \text{traces})$
 ↑
 unit vector in \uparrow direction

- Anti-symmetric tensor: $\mathcal{O}_{[ij]}$
- restricts to $SO(d-1)$ (transverse rot.)
- doesn't contain triv. rep. since $\int_{\text{every comp.}} \exists$ transverse index

- Spinors
- No
- No

NOTE: In this they use broken word identities from dilators and boosts to provide these constraints... I think this is arguing the same point?

• Some result \rightarrow plus interesting constraint in scalar OPE's \rightarrow No vectors, no AS tensors...

$\langle \mathcal{O}(x) \rangle_{\beta} = \frac{\beta}{\Delta_0} \int d^{d-1} y \langle T^{00}(0, y) \mathcal{O}(x) \rangle_{\beta}$ only non-trivial

Loc on provides non-triv. const. on \mathbb{C}_0 of $T=0$ theory

3. Dimensional analysis

• Primary operator $[\mathcal{O}] = \text{length}^{-\Delta}$

• The only length scale is given by β $\therefore \langle \mathcal{O} \rangle \sim \frac{1}{\beta^{\Delta}}$

\rightarrow All together:

$\langle \mathcal{O}^{N_1 \dots N_J} \rangle_{\beta} \sim \frac{\text{bo}}{\beta^{\Delta}} (e^{N_1} \dots e^{N_J} - \text{traces})$
 ↗ from before

Ch 3. Encoding 'bo' in OPE

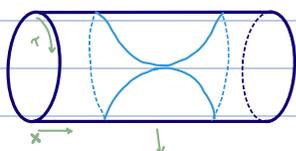
• NOTE: Similarly 2-pt. functions of non-identical operators might not vanish \rightsquigarrow Interesting?

• Focus on identical op's atm.

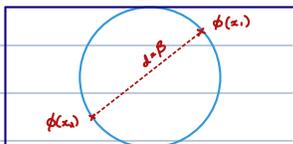
S3.1: When are OPE's valid?

$g(\tau, x) = \langle \phi(x) \phi(0) \rangle_{\beta}$

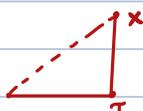
the OPE is valid when both operators lie within a sphere whose interior is flat.



} Largest sphere when $d < \beta$ so we don't get winding (curvature) or self-intersection.



• Largest distance, $x_1 = (0, 0)$, $x_2 = (\tau, x)$ gives $|x_2| = \sqrt{\tau^2 + x^2} < \beta$



→ Radius of convergence: $|x| = \sqrt{\tau^2 + x^2} < \beta$

Compute 3-point $\langle \phi \phi \phi \rangle \sim C \phi \phi \phi \langle \phi \phi \rangle \sim C \phi \phi \phi C_0$
 But $\int \phi \phi \phi = C \phi \phi C_0$

Q: Is $C \phi \phi \phi = \frac{\int \phi \phi \phi}{C_0}$? where C_0 is coeff of 2 pt. zero leg coefficients.

S3.2 Assume radius of convergence

• Use the OPE to get:

$$g(\tau, x) = \langle \phi(\tau, x) \phi(0) \rangle_\beta = \sum_{\Theta \in \phi \times \phi} \frac{C_{\phi \phi \Theta}}{|x|^{2\Delta_\phi - \Delta_\Theta + J \times x_{\mu_1} \dots x_{\mu_J}}} \langle \Theta^{\mu_1 \dots \mu_J}(0) \rangle_\beta + \text{discards}$$

Which we want go to zero!

$$= \sum_{\Theta \in \phi \times \phi} \frac{f_{\phi \phi \Theta}}{C_\Theta} |x|^{\Delta_\Theta - 2\Delta_\phi - J} \times x_{\mu_1} \dots x_{\mu_J} \frac{b_\Theta}{\beta^\Delta} (e^{\mu_1} \dots e^{\mu_J} - \text{traces})$$

• Index contraction: "Gegenbauer polynomial"

$$|x|^{-J} (x_{\mu_1} \dots x_{\mu_J}) (e^{\mu_1} \dots e^{\mu_J} - \text{traces}) = \frac{J!}{2^J (\gamma)_J} C_J^{(\gamma)}(\eta)$$

where $\gamma = \frac{d-2}{2}$, $(a)_n = \frac{\Gamma(a+n)}{\Gamma(a)}$ *↖ Pochhammer symbol*, $\eta = \frac{x}{|x|}$

Therefore

$$g(\tau, x) = \sum_{\Theta \in \phi \times \phi} \frac{a_\Theta}{\beta^\Delta} C_J^{(\gamma)}(\eta) |x|^{\Delta - 2\Delta_\phi}$$

$$\rightarrow a_\Theta \equiv \frac{f_{\phi \phi \Theta}}{C_\Theta} \frac{J!}{2^J (\gamma)_J}$$

• Consider $C_J^{(\gamma)}(\eta) |x|^{\Delta - 2\Delta_\phi}$ to be a 2-pt. conformal block on $S^1 \times \mathbb{R}^{d-1}$

Ch. 4 Some Examples

Sc. 4.1 Free Energy

• Important thermal one-point coefficients is b_T , associated w/ $T^{\mu\nu} = \Theta$, which can be related to the free energy density of the thermal CFT.

• From $\langle \mathcal{O}^{\mu_1 \dots \mu_s}(\vec{x}) \rangle_\beta = \frac{b_{\mathcal{O}}}{\beta^{\Delta}} (\dots)$ the energy density is given by \rightarrow ? Don't get where this comes from... unless we know $F = \frac{b_T}{d} T^d$ (47)

$E(\beta) = -\langle T^{00} \rangle_\beta = -\left(1 - \frac{1}{d}\right) b_T \beta^{-d}$ requiring due to positivity of enrgy $> 0 \therefore b_T = -ve$

$Z(\beta) = \text{Tr } e^{-\beta H} \therefore E(\beta) = -\frac{\partial}{\partial \beta} \log Z = \langle H \rangle_\beta$ in Euclidean $H = \int d^{d-1} x T^{00}(\vec{x})$

$\Rightarrow E(\beta) = \int d^{d-1} x \langle T^{00}(\vec{x}) \rangle_\beta = \int d^{d-1} x \mathcal{E}(\beta)$ $\mathcal{E}(\beta)$ is energy density.

so: $\langle T^{00}(\vec{x}) \rangle_\beta = \frac{b_T}{\beta^{\Delta_T}} (\dots)$ For a CFT, $T_{\mu}^{\mu} = 0$. Thermal states preserve rot. so the ST takes the perfect fluid form

$\Delta_T = d$ $\langle T^{\mu\nu} \rangle = \text{diag}(\mathcal{E}, p, \dots, p)$
 $T_{\mu}^{\mu} = -\mathcal{E} + (d-1)p \therefore \mathcal{E} = (d-1)p, p = -F$

• From dim-analysis, the Free energy density takes the form:

$F = f \beta^{-d}$ where f is a dimensionless quantity $\frac{dF}{dT} = f \frac{d}{dT} T^d = f \cdot d \cdot T^{d-1}$

• From thermodynamics: $F = E - TS = E + T dF/dT = E + f d T^d$

$E = -(d-1)F = -(d-1)(\mathcal{E} + f d T^d)$

$\rightarrow \mathcal{E} + (d-1)\mathcal{E} = -(d-1) f d T^d$

$\mathcal{E} = -\frac{(d-1)}{d} f d T^d$ we know

$= -\left(1 - \frac{1}{d}\right) f d T^d$

Allowed tensor structure

$\langle T^{\mu\nu} \rangle \propto (\mathcal{E} + p) u^\mu u^\nu + p \eta^{\mu\nu}$

$u^\mu = (1, 0, 0, \dots)$ rest frame vector

$\therefore \langle T^{\mu\nu} \rangle \propto \left(\mathcal{E} + \frac{\mathcal{E}}{d-1}\right) u^\mu u^\nu + \frac{\mathcal{E}}{d-1} \eta^{\mu\nu}$ $\hookrightarrow \eta^{00} = -1!$

• $\langle T^{00} \rangle_\beta = \mathcal{E} b_T T^d = -\left(1 - \frac{1}{d}\right) f d T^d$ (48)

• The Ward Identity fixes:

(3) $f \phi \phi T = -\frac{d}{d-1} \frac{\Delta \phi}{S_d}$ $S_d = \text{vol}(S^{d-1}) = \frac{2\pi^{d/2}}{\Gamma(d/2)}$

• The coefficient of T in the thermal block expansion of $\langle \phi \phi \rangle_\beta$ is

$a_T = \frac{S \phi \phi T b_T}{C_T} \frac{J!}{2^s(\tau)^s}$

\rightarrow Plug in (4)

$\rightarrow a_T = -f S_d \frac{2\Delta \phi}{d-2} \frac{C_{\text{free}}}{C_T}$ where $C_{\text{free}} = \frac{d}{d-1} \frac{1}{S_d^2}$ $T^{\mu\nu}$ apt. coeff. for free boson in d dim.

• For a single real scalar

$$b_T = -2d \zeta(d) / S_d$$

$$F = \int T^d = T \int \frac{d^{d-1} k}{(2\pi)^{d-1}} \log [1 - e^{-\beta |k|}] = -\frac{2}{S_d} \zeta(d) T^d$$

- Some known results!

1. For the free scalar in three dimensions, we have $b_T^{\text{free}} = -6\zeta(3)/(4\pi) \approx -0.57394$.
2. For the $O(N)$ model in three dimensions at leading order in $1/N$, $b_T = 4N/5 \times b_T^{\text{free}} \approx -0.45915N$ [57, 48]. We will derive this from our inversion formula in section 5.1.
3. In the Monte Carlo literature, the quantity f is known as the "Casimir Amplitude". For the Ising model, Monte Carlo results give $f \approx -0.153$ [58-60], with numerical errors in the third digit. This translates to $b_T^{\text{Ising}} \approx -0.459$. Note that b_T^{Ising} is remarkably close to the value of b_T/N for the $O(N)$ model at large N .¹⁴