

The Milnor-Svarc lemma, generalised:

The Milnor-Svarc lemma: $G \curvearrowright X$, where X is a proper geodesic space, and the action is proper discontinuous and cocompact, then

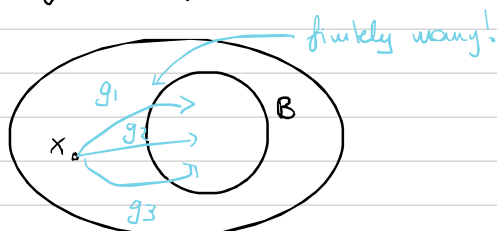
$$\text{Cay}(G, S) \stackrel{\text{QI}}{\cong} X$$

finite generating set $\xrightarrow{\quad} \text{QI} = \text{quasi-isometry}$

Aim: Weaken the assumptions and prove it still works!

Properly discontinuously $\rightarrow$ discontinuously $\star$ But we have to assume G fin gen^{ed}
 proper geodesic space $\rightarrow$ geodesic space.

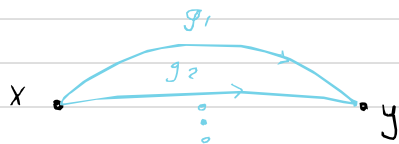
Defn: Properly discontinuous:
 only finitely many $g \in G$ send x into the ball B



Defn: Discontinuous: We can now have infinitely many $g \in G$ sending x into B .

Discontinuity asserts that the points in the orbit of x don't "dump up".

Stabilisers: $\xrightarrow[\text{disc}]{\text{action prop}}$ stabilisers are finite
 $\xrightarrow{\text{action disc}}$ stabilisers can be infinite



claim: $g_2^{-1} g_1 x = x$

Proof: $d(g_2^{-1} g_1 x, x) = d(g_1 x, g_2 x) = y$
 because we assumed $g_1, g_2 \in \text{Stab}(x)$.

$\text{Stab}(x) \supseteq \{g_i^{-1} g_j\}$

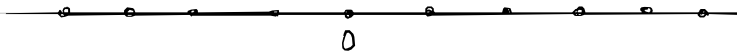
Conversely, if we have infinitely many $g \in G$ that send x to itself, we can make new (infinite) stabilisers by composing g with $g_i^{-1} g_j$

Examples:

1) $G = \mathbb{Z}^2$, $X = \mathbb{R}$ $G \curvearrowright X$ $(a, 0)(x) = x + a$, $(0, b)(x) = x$

Picture:

Stabilisers of Δ are all points $(0, b)$
as many!



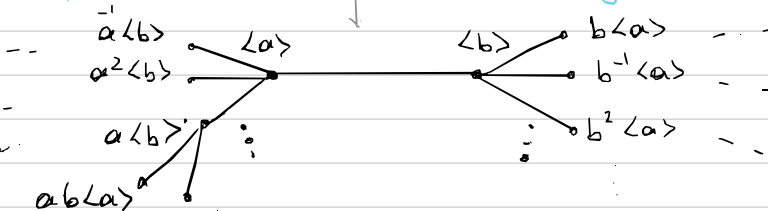
Claim: Action is cocompact + discontinuous but not properly discontinuous

2) $G = F_2$, $X = T_{\text{Bass-Serre}}$ note $F_2 \geq \langle a \rangle$
 $\geq \langle b \rangle$

Vertices $\swarrow$
are left cosets
of the subgroups
 $\langle a \rangle, \langle b \rangle$.

Edges: $\langle a \rangle \cdot \dots \cdot a^i \langle b \rangle$

the word that comes before has to belong in L_{a-1}



Action: $h\langle a \rangle \cdot g = gh\langle a \rangle$ ← closed balls are not compact!

This is not a proper space or a proper disc. function! $\leadsto$ vertices have ∞ stabilisers $\rightarrow \text{Stab}(\langle a \rangle) = \{g \in G \mid g \langle a \rangle = \langle a \rangle\} \iff g \in \langle a \rangle$

But $\langle a \rangle$ is infinite!

→ what about stabilisers of vertices of the form $h\langle a \rangle$?

$$\text{Stab}(h\langle\alpha\rangle) = \{g \in G : gh\langle\alpha\rangle = h\langle\alpha\rangle\} \Leftrightarrow h^{-1}gh \in \langle\alpha\rangle$$

have something of the form, say $a \langle b \rangle a^{-1}$ stabilises $a \langle b \rangle$!

How can we find a way to relate the two geometries?

(1) Find maximum stabiliser subgroups

for (i) $\leadsto$  $\langle (a, 1) \rangle$ hence it is

for (ii) $\leadsto$  $\langle (a, 1) \rangle$ we get $\langle (a, 1) \rangle$ and $\langle (a, 1) \rangle$

(2) Choose one representative per conjugacy class.

$\{ \langle 1 \rangle \}$

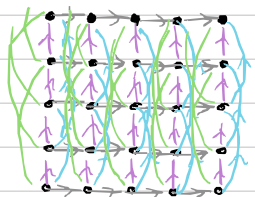
$\{ \langle 2 \rangle \}$

$\langle (0,1) \rangle$

$\langle a \rangle, \langle b \rangle$

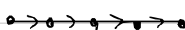
Now, for **example 1**, take the generating set $\langle (1,0), (0,1) \rangle$, and take $\mathbb{Z}^2 = \langle (1,0), (0,1), (0,2), (0,3), \dots \rangle$

and construct a Cayley graph for $\mathbb{Z}^2$ with respect to this new, infinite generating set!



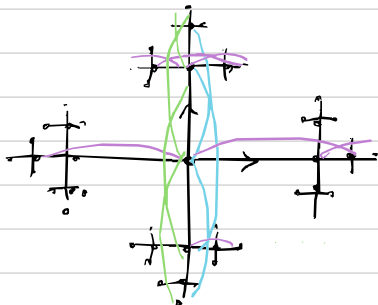
horizontally we have the same graph as before!

$\cong$
Q1



idea: "coning off"

For **example 2**: $F_2 = \langle a, b \rangle$ but instead take $F_2 = \langle a, b, a^2, a^3, \dots, b^2, b^3, \dots \rangle$ and construct the Cayley graph wrt this generating set:



Q1

$\cong$

Bass-Serre tree!

again, "coning off"

↓

idea, everything in $\langle a \rangle$ is dist.

1 from each other

Same for everything in $\langle b \rangle$

Hence we send all points on horizontal lines to $\langle a \rangle$

and vertical lines to $\langle b \rangle$

Charney - Crisp

↓

$= \langle T \rangle$

Theorem: G fin. gen'd, $G \curvearrowright X$, where X is a length space

and the action is discontinuous and cocompact.

just about weaker than geodesic space.

Let S be the family of maximal stabiliser subgroups

Let φ be one representative for each conj class in S .

Then $\text{Cay}(G, T \cup \varphi)$ is quasi-isometric to X .

Example: The trivial action $X \supset \{x\}$ $\mathcal{G} = G$.
 $\text{Cay}(G, G)$ is all the vertices' with edges from anything $\in V$ to anything $\in V$. {vertices} ↓

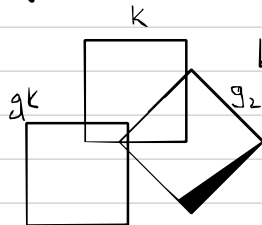
Questions: Difference between cutting off and quotienting?

→ If we quotient, we might not end up with a Cayley graph.
 With cutting off, we don't act on the things we cut-off anymore, hence we still get a Cayley graph.

Some ideas from the proof of the theorem:

→ We want to show $|\mathcal{G}| < \infty$ " $\mathcal{G}$ is a finite set of Subgroups".
 i.e. finite number of conj. classes in our collection of stabilisers.

$\begin{matrix} x_1 & x_2 \\ \vdots & \vdots \end{matrix}$ $K \in \mathcal{G}$
 ↑
 countably many x_i
 ↓
 $\{x_i\}$ converge to $x \in K$



K fundamental domain, we want the orbit of K to cover all stab.

This is true by local compactness.

Suppose we have infinite $F_1, F_2, \dots$ st

$$F_1 = \text{stab}\{x_1\}$$

$\vdots$

$$F_i = \text{stab}\{x_i\}$$

$\vdots$

This will contradict discontinuity of our action:

* $d(g_i(x), x) \leq 2 \underbrace{d(x_i, x)}_{\rightarrow 0}$ hence $g_i \rightarrow x$

This contradicts discontinuity! Hence we cannot have infinitely many F_i .

→ This is true since $d(g_i(x), x) \leq \underbrace{d(g_i(x), x_i)}_{\rightarrow 0} + d(x_i, x)$

$$= d(g_i(x), g_i(x_i)) = d(x, x_i) \text{ by isometry.}$$

End of talk 1!